







Mechanical fields computed

by the multi-scale method

Comparison of multi-scale methods for modeling perforated plate in computational structural mechanics

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Introduction Riveted assembly modeling Mechanical fields computed by a fine mesh Physical phenomena Stress, strain concentrated Refined **Difficulties** mesh FEM Incompatibility (assembly size vs structure) Multi-scale Multiscale methods method Super-element: Hybrid-Trefftz displacement (HT-D) element

Figure 1: Modeling of riveted assembly areas of an aeronautical structure (by a fine mesh or a multi-scale method)

combined TFA – Mori-Tanaka (MT) Hybrid-Trefftz displacement element **HT-D** principle **Boundary field:** Compatibility with the neighboring FE Interior field Boundary field Nc Kolosov - Muskhelishvili Interior field $\widetilde{\mathbf{u}} = \mathbf{N}\mathbf{q}$ Kolosov-Muskhelishvili (KM) analytical solution for linear perforated membrane Figure 2: Displacement fields in the HT-D method **Practical use** Mesh HT-D element Structure

Homogenization: Integrated

Transformation Fields Analysis (TFA) and

Figure 3: Using the HT-D element in structural computations

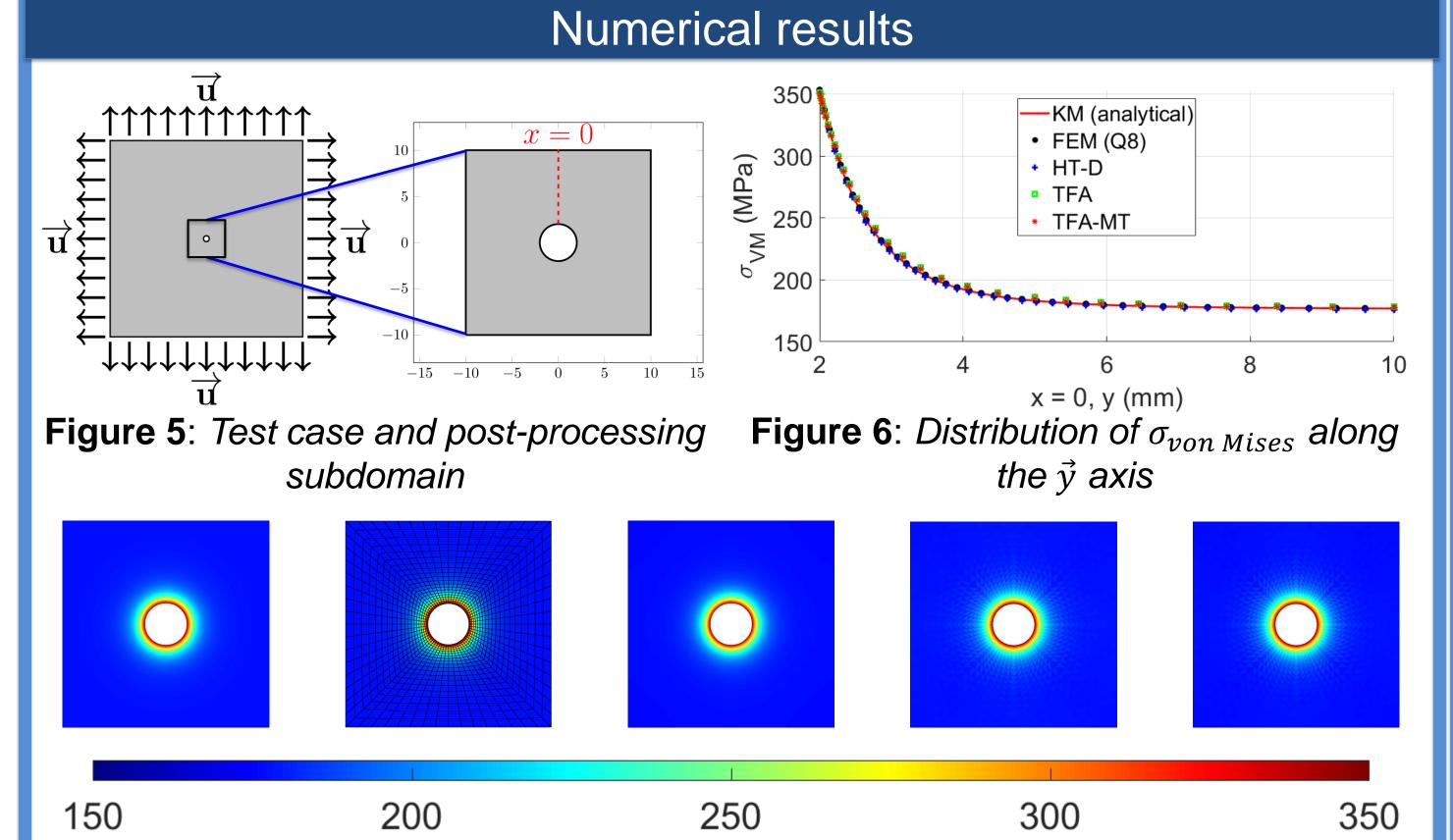


Figure 7: Distribution of the von Mises stress over the post-processing subdomain. From left to right: KM (analytical), FEM (Q8), HT-D, TFA and TFA – MT

Method	$\max(\sigma_{von\ Mises})$ (MPa)	Error %	Computational time (s)
KM (analytical)	353.0	-	-
FEM (Q8)	353.2	0.06	5.5
HT-D	351.3	0.5	0.08
TFA	351.3	0.5	980
TFA – MT	350.0	8.0	0.07

References

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[3] J. L. Chaboche, S. Kruch, J. F. Maire, and T. Pottier, "Towards a micromechanics based inelastic and damage modeling of composites," *International Journal of Plasticity*, vol. 17, no. 4, pp. 411–439, Jan. 20015.

Homogenization method (TFA and combined TFA – MT) TFA integrated homogenization method (3) Homogenization step (1) Localization step $\boldsymbol{\varepsilon}_r = \boldsymbol{A}_r : \boldsymbol{E} + \sum \boldsymbol{D}_{rs} : \boldsymbol{\varepsilon}_s^{in}$ Refined mesh (N sub volumes) ⇒ a priori expensive (2) Integration step $\sigma_r = f(\varepsilon_r)$ MT integrated homogenization method RVE (3) Homogenization step (1) Localization step $\Omega_{\mathbf{2}}$ $\mathbf{\Sigma} = c_1 \mathbf{\sigma}_1 + c_2 \mathbf{\sigma}_2$ $\boldsymbol{\varepsilon}_{1,2} = \boldsymbol{A}_{1,2} : \boldsymbol{E} + \sum \boldsymbol{D}_{1s,2s} : \boldsymbol{\varepsilon}_s^{in}$ 2 sub volumes ⇒ no localization (2) Integration step $\sigma_{1,2}$ $\sigma_{1,2} = f(\varepsilon_{1,2})$ **Combined integrated TFA – MT** $\boldsymbol{\varepsilon}_r = \boldsymbol{A}_r : \boldsymbol{E} + \sum_{s}^{N} \boldsymbol{D}_{rs} : \boldsymbol{\varepsilon}_s^{in}$ $\sigma_r = B_r: \Sigma - \sum_{s=1}^n F_{rs}: L_s: \varepsilon_s^{in}$ **TFA** numerical localization TFA numerical localization (4) Post-processing Homogenization (1) Localization step (3) Homogenization step $\boldsymbol{\varepsilon}_{1,2} = \boldsymbol{A}_{1,2} : \boldsymbol{E} + \sum_{S=1}^{\infty} \boldsymbol{D}_{1S,2S} : \boldsymbol{\varepsilon}_{S}^{in}$ $\mathbf{\Sigma} = c_1 \mathbf{\sigma}_1 + c_2 \mathbf{\sigma}_2$ $\Omega_{\mathbf{2}}$ Mori-Tanaka Mori-Tanaka (2) Integration step $\sigma_{1,2} = f(\varepsilon_{1,2})$ \longrightarrow $\sigma_{1,2}$ **Practical use** Mesh Element with the Structure homogenization behavior

Conclusion and prospects

Figure 4: Homogenization method in structural computations

- All methods were able to correctly localize the fields in the linear structural multiscale model.
- The HT-D super-element was very accurate in the test case, but it is limited to linear computations.
- The TFA method was too costly to be used in modeling the perforated structure.
- The combined TFA MT method exhibited similar efficiency to the HT-D method.
- To address materially nonlinear problems, only the combined TFA MT method seems promising in terms of cost-effectiveness.